

Phys 410
Fall 2015
Lecture #3 Summary
8 September, 2015

We discussed the motion of a charged particle in a uniform and uni-directional magnetic field \vec{B} , subject to the Lorentz force $\vec{F} = q\vec{v} \times \vec{B}$, where q is the charge of the particle. We took $\vec{B} = B\hat{z}$ and found that Newton's second law of motion reduces to three scalar equations: $m\dot{v}_x = qv_yB$, $m\dot{v}_y = -qv_xB$, and $m\dot{v}_z = 0$. The solution for the motion along the magnetic field direction is simple: $z(t) = z_0 + v_{z0}t$, which is uniform motion at constant velocity. We solved the x-y plane motion using the trick of mapping this two-dimensional problem into the complex plane. Define the complex variable $\eta \equiv v_x + iv_y$, where $i = \sqrt{-1}$. The velocity of the particle is now represented as a point in the complex η plane, and the solution for the velocity evolution with time is a trajectory in the complex η plane. The pair of coupled differential equations now reduces to a simple equation for the time evolution of η , namely $\dot{\eta} = -i\omega\eta$, and the Cyclotron frequency is defined as $\omega = qB/m$, for the charged particle of mass m .

Note that this use of the complex η function is simply a mathematical bookkeeping device which is used to simplify the solution of the problem. All measurable quantities must have two characteristics: they must be real numbers and they must be finite in magnitude. Hence when we compare to experiment we must take the real and imaginary parts of η : $v_x(t) = \text{Re}[\eta(t)]$ and $v_y(t) = \text{Im}[\eta(t)]$.

The equation is solved as $\eta = \eta_0 e^{-i\omega t}$, where $\eta_0 = v_{x0} + iv_{y0} \equiv v_0 e^{i\delta}$. This equation represents uniform circular motion in the η -plane on a circle of radius v_0 starting at an angle δ and rotating clockwise with angular velocity ω . The initial velocities are related to v_0 and δ as $v_{x0} = v_0 \cos\delta$ and $v_{y0} = v_0 \sin\delta$, and $v_0 = \sqrt{v_{x0}^2 + v_{y0}^2}$, $\delta = \tan^{-1}(v_{y0}/v_{x0})$. The resulting description of the motion can be obtained by taking the real and imaginary parts of η as $v_x(t) = \text{Re}[\eta] = v_0 \cos(\delta - \omega t)$, and $v_y(t) = \text{Im}[\eta] = v_0 \sin(\delta - \omega t)$.

The trajectory of the particle in the xy-plane can be solved by a similar method. First define the complex variable $\xi \equiv x + iy$, and relate it to η through the time derivative: $\eta = \dot{\xi}$. Integrate this equation and apply the initial conditions for x and y to obtain $\xi(t) = r_0 e^{i(\phi_0 - \omega t)}$, where the initial positions are written as $x_0 + iy_0 = r_0 e^{i\phi_0}$. The particle motion is described by uniform circular motion around a circle of radius r_0 starting at angle ϕ_0 at angular velocity ω . The resulting motion in three dimensions is helical about the magnetic field (z) axis.

We considered several [applications](#) of these ideas to the [cyclotron](#), the mass spectrometer, the Calutron, and [Whistlers](#) in the magneto-sphere of the earth.

We recalled the definition of the total momentum \vec{P} of a many particle system as simply the sum over all the particles of the elementary momentum of each particle, $\vec{P} = \sum_{\alpha=1}^N \vec{p}_{\alpha} = \sum_{\alpha=1}^N m_{\alpha} \vec{v}_{\alpha}$. If the particles in the system interact with each other by means of forces that obey Newton's third law of motion, the change in total momentum is simply the result of a net external force: $\dot{\vec{P}} = \vec{F}_{net}^{ext}$. This is a generalization of Newton's second law of motion to extended systems. An important consequence is that if the net external force is zero, then the total momentum of the many-particle system is conserved. This is true independent of the nature of the forces between the particles in the system, be they electromagnetic, nuclear, conservative or non-conservative (i.e. forces that convert mechanical energy in to 'heat').